

# HIT YOUR TARGET IN ANY ENVIRONMENT

# **TALIN**

## Flexible, reliable, best-value INS/GPS navigator

### **SYSTEM FEATURES**

- Honeywell's next generation ring laser gyro technology, combined with our best-in-class accelerometers, for unparalleled performance in the most demanding military and commercial environments, without the need for secondary shock isolation.
- Single system plug "N" play across multiple platforms - autoconfiguration adaptable
- Instant on! On-the-move alignment
- Multiple accuracy configurations to meet different applications requirements
- Over 15,000 TALIN systems fielded on over 60 military and commercial platforms worldwide, including combat vehicles, sensor platforms, towed and self-propelled weapons, survey applications, and mining equipment
- Available in different configurations to support higher shock and extreme artillery requirements

### **SYSTEM CHARACTERISTICS**

### **Operating Ranges**

- Attitude: Alignment and orientation in any direction and on the move
- Angular Rate: ±200 deg/sec

### Reliability

 MTBF: >50,000 hours (TALIN demonstrated)

### **Power Requirements**

• 18-32 Vdc: <26 watts\*

### **Thermal Operating Range**

No cooling required:
-46°C to 71°C (-51°F to 160°F)

### **Navigation Sensors**

- Standard/Internal: 3-axis inertial sensors
- Optional/External: VMS, PLGR, DAGR

### Software

- Modular partitioned for costeffective system missionization
- Field upgradeable

### Weight

• <13 pounds (<6kg)

### Interfaces

• Standard:

TALIN/gTALIN: 1553A & B/RS-422/ RS-232 serial host interface eTALIN: Ethernet

- Optional: Additional RS-422/RS-232 data interface, turret encoder, laser range finders
- Form Factor (excluding flanges & connectors)
- Approx. 5.4 H x 7.6 W x 8.6 L inches
- Approx. 14 H x 19 W x 22 L cm

### Installation

• Can be hard mounted in any orientation

\*Application and configuration dependent



| PERFORMANCE   | TALIN 2000                           | TALIN 3000                           | TALIN 4000                           | TALIN 5000                           |
|---|--------------------------------------|--------------------------------------|--------------------------------------|--------------------------------------|
| POSITION ACCURACY                                     |                                      |                                      |                                      |                                      |
| Horizontal position error CEP with VMS aiding         | 3 m < 2 km DT<br>0.20% DT* > 2 km DT | 2 m < 2 km DT<br>0.19% DT* > 2 km DT | 2 m < 2 km DT<br>0.18% DT*> 2 km DT  | 2 m < 2 km DT<br>0.15% DT*+> 2 km DT |
| Horizontal position error CEP with ZUPT/VMS aiding    | 9 m < 5 km DT<br>0.10% DT* > 5 km DT | 6 m < 5 km DT<br>0.07% DT* > 5 km DT | 5 m < 5 km DT<br>0.06% DT* > 5 km DT | 5 m < 5 km DT<br>0.05% DT* > 5 km DT |
| Vertical position error PE with VMS aiding            | 10 M OR<br>0.1 % DT*                 | 10 M OR<br>0.1 % DT*                 | 10 M OR<br>0.1 % DT*                 | 10 M OR<br>0.06 % DT* †              |
| HEADING/POINTING ACCURACY                             |                                      |                                      |                                      |                                      |
| Specified accuracy (RMS) at ±65° latitude             | <4 mils                              | <2 mil                               | <1 mil                               | <0.7 mil                             |
| Typical accuracy (RMS) at<br>Indian (<±40° )latitudes | <2.2 mils                            | <1.11 mil                            | <0.54 mil                            | <0.4 mil                             |
| SEC (LAT)   | <1.69 mils                           | <0.85 mils                           | <0.42 mils                           | <0.3 mils                            |
| Pitch and roll accuracy (RMS)                         | <1.00 mils                           | <1.00 mils                           | <0.50 mils                           | <0.35 mils                           |

Values shown are per definitions in TALIN system specifications

\* with Offset 2 meters † Based on empirical data

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**MAKE IT**